

EAM300-SM6.5U4G.13120.A

Solid shaft with synchro flange, magnetic multiturn encoder 13 bit ST / 12 bit MT

Article number: 11273671

Overview

- Encoder multiturn / SSI
- Precise magnetic sensing
- Angular accuracy up to ±0.15°
- Resolution 25 bit (13 bit ST, 12 bit MT)
- High resistance to shock and vibrations
- High protection IP 65
- Axial cable connection



Technical data			
Technical data - electrical ratings			
Voltage supply	4.530 VDC		
Consumption typ.	60 mA (5 VDC, w/o load) 20 mA (24 VDC, w/o load)		
Initializing time	≤ 170 ms after power on		
Data currency	Typ. 2 µs (cyclic request)		
Interface	SSI		
Function	Multiturn		
Operating mode	Linear feedback shift register (on request)		
Steps per revolution	8192 / 13 bit		
Number of revolutions	4096 / 12 bit		
Absolute accuracy	±0.15 ° (+20 ±15 °C) ±0.25 ° (-40+85 °C)		
Sensing method	Magnetic		
Code	Gray		
Code sequence	CW: ascending values with clockwise sense of rotation (looking at flange)		
Inputs	SSI clock: Linereceiver RS422 Zero setting input Counting direction		
Output stages	SSI data: Linedriver RS422		
Interference immunity	EN 61000-6-2		
Emitted interference	EN 61000-6-3 (cable length <30 m, no connection to DC network) EN 61000-6-4		

Technical data - electrical ratings				
Diagnostic function	DATAVALID (on request)			
Approval	UL approval / E217823			
Technical data - mechanical design				
Size (flange)	ø30 mm			
Shaft type	ø6 x 12 mm solid shaft			
Flange	Synchro flange			
Protection EN 60529	IP 65 (without shaft seal)			
Operating speed	≤6000 rpm			
Starting torque	≤0.75 Ncm (+20 °C)			
Moment of inertia	0.98 gcm ²			
Admitted shaft load	≤10 N axial ≤10 N radial			
Material	Housing: steel zinc-coated Flange: aluminium Shaft: stainless steel			
Operating temperature	-40+85 °C (see general information)			
Relative humidity	95 %			
Resistance	EN 60068-2-6 Vibration 30 g, 10-2000 Hz EN 60068-2-27 Shock 500 g, 1 ms			
Weight approx.	150 g			
Connection	Cable 2 m			

Page 1 of 4

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General information

Self-heating interrelated to speed, protection, attachment method and ambient conditions as well electronics and supply voltage must be considered for precise thermal dimensioning. Self-heating is supposed to approximates 6 K (standstill) and additionally for movement 1.5 K per 1000 rpm (IP 65) or 3.5 K per 1000 rpm (IP 67). Operating the encoder close to the maximum limits requires measuring the real prevailing temperature at the encoder flange.

Terminal assignment Cable for connection reference -L and -U Core colour Signals Description brown +Vs Voltage supply white 0 V Voltage supply green Clock+ Clock signal Clock-Clock signal yellow Data signal Data+ grey pink Data-Data signal SET Zero setting input blue red DIR Counting direction input

Screen: connected to housing Cable data: 8 x 0.09 mm²

Terminal significance

SET	Zero setting. Input for zero setting at any position. The zero setting operation is triggered by a high pulse and has to be in line with the selected direction of rotation (DIR). Impulse duration >100 ms. Connect to 0 V after zero setting for maximum interference immunity.
DIR	Counting direction input. The input is standard on high. For maximum interference immunity connect to +Vs respectively 0 V depending on counting direction. CW HIGH - CCW LOW (Version with DATAVALID does not include the counting directon input).

Trigger level		
Control inputs	Input circuit	
Maximal	0+Vs	
Input level Low	<1 V	
Input level High	>2.1 V	

Applies to standard cable lengths up to 2 m, for longer cables the voltage drop must be taken into account.

Data transfer Output signal nΤ Clock t2 Data

 $T = 0.5...10 \mu s$ $t_1 = 0.25...5 \mu s$ f max. = 2 MHz $t_2 = 20 \pm 2 \mu s$

Data acquisition time ta

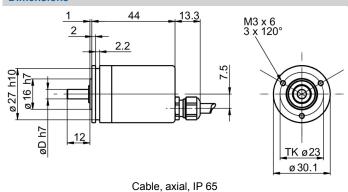
Following timing of the SSI Masters is the requirement for a data refresh rate of typ. 2 µs. If this is not fulfilled the data refresh rate is <50 µs. ta <5000 µs

ta jitter <±2 μs Clock Data

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Dimensions



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Absolute encoders/MAGRES

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Accessories

Mounting accessories

10106004 Clamp set ø10 mm