

Through hollow shaft

Optical multiturn encoders up to 21 bit ST / 16 bit MT

Overview

- Encoder multiturn / bus cover
- Optical sensing method
- Resolution: singleturn 21 bit (default: 13 bit), multiturn 16 bit (default: 16 bit)
- Total resolution up to 31 bit
- Through hollow shaft
- Interface: CANopen®
- Internal continuity check with diagnostic information by bus
- Maximum resistant against magnetic fields
- Gear factor adjustable via numerator / denominator
- Dynamic PDO-mapping



Picture similar

Technical data			
Technical data - electrical r	atings	Technical data - mechan	
Voltage supply	830 VDC	Size (flange)	
Reverse polarity protection	Yes	Shaft type	
Consumption w/o load	≤100 mA (24 VDC)		
Initializing time typ.	180 ms after power on	Protection EN 60529	
Interface	CANopen®		
Function	Multiturn	Operating speed	
Profile conformity	CANopen® CiA 301 V4.2.0	Starting acceleration	
Node-ID	Adjustable via rotary switches in bus cover or interface	Starting torque	
Steps per revolution	≤2097152 / 21 bit	Motor shaft tolerance	
Number of revolutions	≤65536 / 16 bit		
Absolute accuracy	±0.01 °	Material	
Sensing method	Optical		
Code	Binary		
Interference immunity	EN 61000-6-2		
Emitted interference	EN 61000-6-3	Operating temperature	
Programmable parameters	Steps per revolution Number of revolutions	Relative humidity	
	Preset Scaling Rotating direction Gear factor	Resistance	
Diagnostic function	Position or parameter error Multiturn sensing	Weight approx.	
	Operating hour counter	Connection	
Status indicator	DUO-LED integrated in bus cover	Instruction	
Approval	UL approval / E217823		

Technical data - mechanica	ai design
Size (flange)	ø58 mm
Shaft type	ø12 mm (through hollow shaft)ø14 mm (through hollow shaft)
Protection EN 60529	IP 54 (without shaft seal) IP 65 / IP 67 (with shaft seal)
Operating speed	≤6000 rpm (+25 °C)
Starting acceleration	≤1000 U/s²
Starting torque	≤0.04 Nm (+25 °C, IP 54) ≤0.06 Nm (+25 °C, IP 65 / IP 67)
Motor shaft tolerance	± 0.2 mm (axial offset) ≤ 0.1 mm (radial offset) ≤ 0.1 mm (concentricity)
Material	Housing: aluminium Flange: aluminium Bus cover: zinc die-cast Shaft: stainless steel
Operating temperature	-25+85 °C (see general information) -40+85 °C (see general information)
Relative humidity	95 % non-condensing
Resistance	EN 60068-2-6 Vibration ±0.75 mm - 10-58 Hz, 10 g - 58- 2000 Hz EN 60068-2-27 Shock 200 g, 3 ms
Weight approx.	600 g
Connection	Cable gland
Instruction	Resonance frequency with stator coupling (11721627): 450600 Hz

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General information

Self-heating correlated to installation and ambient conditions as well as to electronics and supply voltage must be considered for precise thermal dimensioning. Operating the encoder close to the maximum limits requires measuring the real prevailing temperature at the encoder flange.

Terminal assignment		
Signals	Description	
GND	Ground connection relating to UB	
UB	Voltage supply	
CAN_H	CAN bus signal (dominant High)	
CAN_L	CAN bus signal (dominant Low)	

Terminals of the same significance are internally connected and identical in their functions. Max. load on the internal terminal connections UB-UB and GND-GND is 1 A each.

Terminating resistor

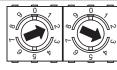


Switch 1: ON = final user OFF = user X

Default: OFF

Switch 2: Without function

Node-ID

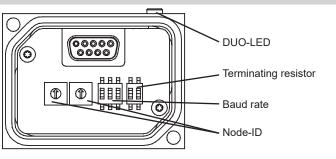


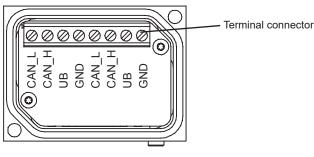
Defined by rotary switch (Node-ID 01 to 99). If a higher node ID is required use the CANopen configuration.

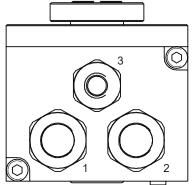
If the rotary switch is set to 00, the Node-ID and the baud rate can be configured via the CANopen objects 2101h (Node-ID) and 2100h (baud rate).

Example: 23 Default: 00

View inside bus cover







Cable: 1, 2 = \emptyset 8-10 mm (-40-85 °C) / \emptyset 5-9 mm (-25-85 °C) Cable: $3 = \emptyset 4.5-6 \text{ mm } (-40-85 ^{\circ}\text{C}) / \emptyset 3-6 \text{ mm } (-25-85 ^{\circ}\text{C})$

Baud rate



Baud rate	Dip switch position			
	1	2	3	
10 kBit/s*	OFF	OFF	OFF	
20 kBit/s*	OFF	OFF	ON	
50 kBit/s	OFF	ON	OFF	
125 kBit/s	OFF	ON	ON	
250 kBit/s	ON	OFF	OFF	(default)
500 kBit/s	ON	OFF	ON	
800 kBit/s	ON	ON	OFF	
1 MBit/s	ON	ON	ON	

The baud rate 100 kBit/s can only be configured via CANopen object (2100h).

* not supported

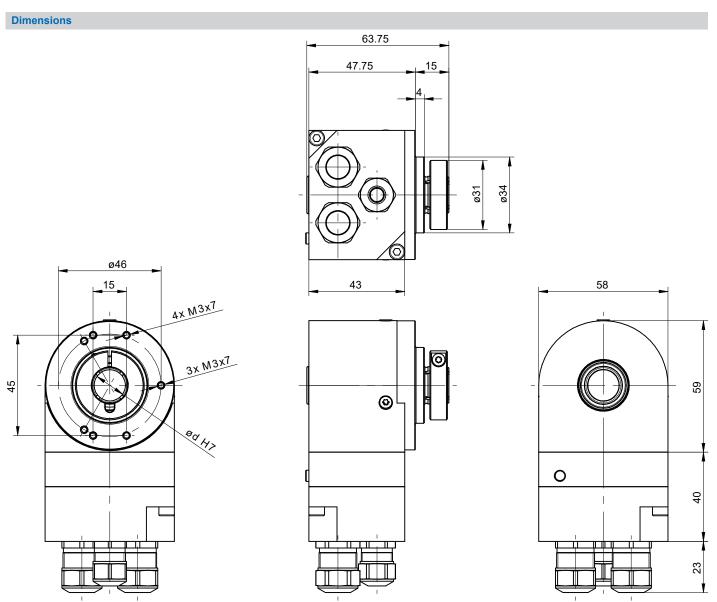
CANopen® features

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Operating modes	Timer-driven (Event-Time) Synchronously triggered (Sync)
Node Monitoring	Heartbeat Node guarding
Programmable parameters	Scaling Rotating direction Electronic gear function (adjustable via numerator / denominator) MUR (Measuring Units per Revolution) TMR (Total Measuring Range) Speed configuration Operating modes
Diagnosis	Multiturn sensing Position error Battery level
Functions	Electronic gear function Dynamic PDO mapping Preset value LED status



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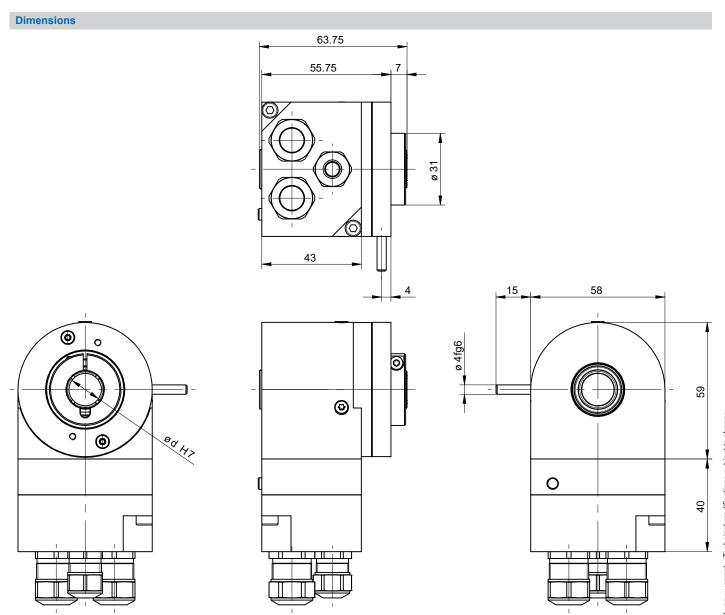


EN580C.ML-T - cable gland, clamping ring on flange



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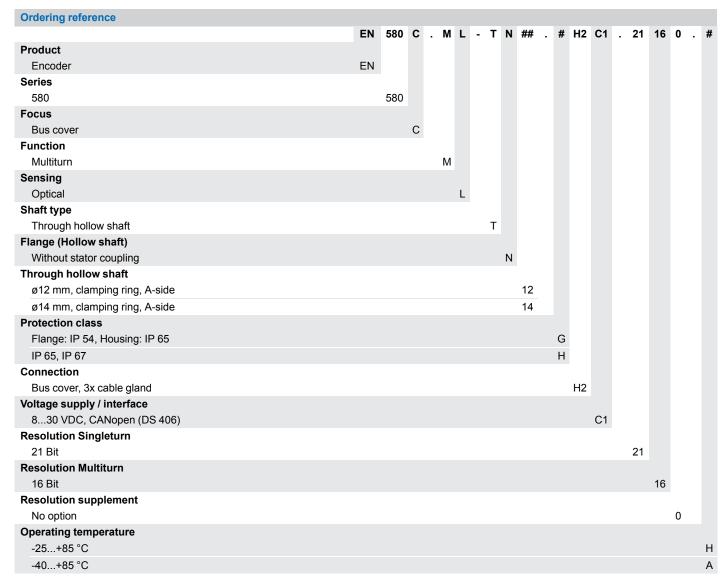


EN580C.ML-T - cable gland, clamping ring on flange, option MTQ003: torque pin



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Α	CC	es	SS	or	ies

Mour	itina	access	ories

10139345	Torque support by rubber buffer for encoders with 15
10100010	rorquo cupport by rubbor bunor for chicouche with re-

mm pin (Z 119.041)

11721627 Stator coupling, 2-armed (mounting kit 207)